

Math 4200-001

Week 2 concepts and homework

1.5

Due Wednesday September 9 at 5:00 p.m.

1.5 1ad, 3b, 5c, 6c (in 5c and 6c describe the differential map as a rotation-dilation); 8, 9, 10, 11, 16, 18abc, 19.

w2.1a) Consider  $f(z) = \frac{1}{z}$  and  $z_0 = \frac{1+i}{2}$ . Illustrate the rotation-dilation differential map for  $f$  at  $z_0$  using rectangular coordinates. Precisely, Sketch a domain picture containing the point  $z_0$  along with real and imaginary coordinate segments through that point having unit tangent vectors  $1$  and  $i$ . Sketch a range picture containing  $f(1+i)$ , the images of the coordinate segments with the corresponding image tangent vectors based at  $f(z_0)$  - which should be rotated and dilated according to the argument and absolute value of  $f'(z_0)$ .

w2.1b) Repeat part (a), except using polar form. In other words, for

$f(re^{i\theta})$ ,  $r_0 = \frac{1}{\sqrt{2}}$ ,  $\theta_0 = \frac{\pi}{4}$ , sketch  $r$  and  $\theta$  coordinate segments through  $z_0$  and their tangent vectors. In the range picture sketch the images of these coordinate segments and the corresponding rotated and dilated image tangent vectors.

In the problem above you are creating concrete realizations of the schematic pictures Figures 1.5.1 and 1.5.2 in the text.

Math 4200

Friday September 4

1.5 continued: The Cauchy-Riemann equations, chain rules, and the differential map

Announcements We'll talk about the Cauchy Riemann equations and Theorem in Wednesday's notes, and then discuss the chain rule and the differential map in today's notes. We'll briefly discuss the local inverse function theorem as well, leaving the in depth proofs of the Cauchy Riemann Theorem and local inverse function theorem until Wednesday next week. Each depends on key results from Math 3220, which we will state and articulate carefully to the present context. (The text omits both proofs.)

Warm-up exercise

Our general discussion today will use the affine approximation characterization of complex differentiability. It is analogous to discussions you had in Math 3210-3220 when you discussed the "differential" or "differential matrix".

Lemma:  $f'(z_0)$  exists and has value  $c$  if and only if we have the affine approximation formula with error estimate:

$$f(z_0 + h) = f(z_0) + c h + h \varepsilon(h)$$

where  $\varepsilon(h) \rightarrow 0$  as  $h \rightarrow 0$ .

check:

### Chain rules

1) Theorem (Chain rule for composition of analytic functions): If  $f$  is differentiable at  $z_0$  and  $g$  is differentiable at  $f(z_0)$  then  $g \circ f$  is differentiable at  $z_0$ , and

$$(g \circ f)'(z_0) = g'(f(z_0))f'(z_0)$$

proof: We use the affine approximation formula for  $g$  at  $f(z_0)$ :

$$g(f(z_0 + h)) = g(f(z_0)) + g'(f(z_0))(f(z_0 + h) - f(z_0)) + k \varepsilon(k)$$

for

$$k = f(z_0 + h) - f(z_0)$$

rewrite, divide by  $h$ :

$$\frac{g(f(z_0 + h)) - g(f(z_0))}{h} = g'(f(z_0)) \frac{f(z_0 + h) - f(z_0)}{h} + \frac{k}{h} \varepsilon(k)$$

Take limits as  $h \rightarrow 0$  and note that the last term  $\rightarrow 0$  because  $\frac{k}{h} \rightarrow f'(z_0)$  and

$\varepsilon(k) \rightarrow 0$ , since  $k \rightarrow 0$  by the continuity of  $f$ .

$$(g \circ f)'(z_0) = g'(f(z_0))f'(z_0).$$

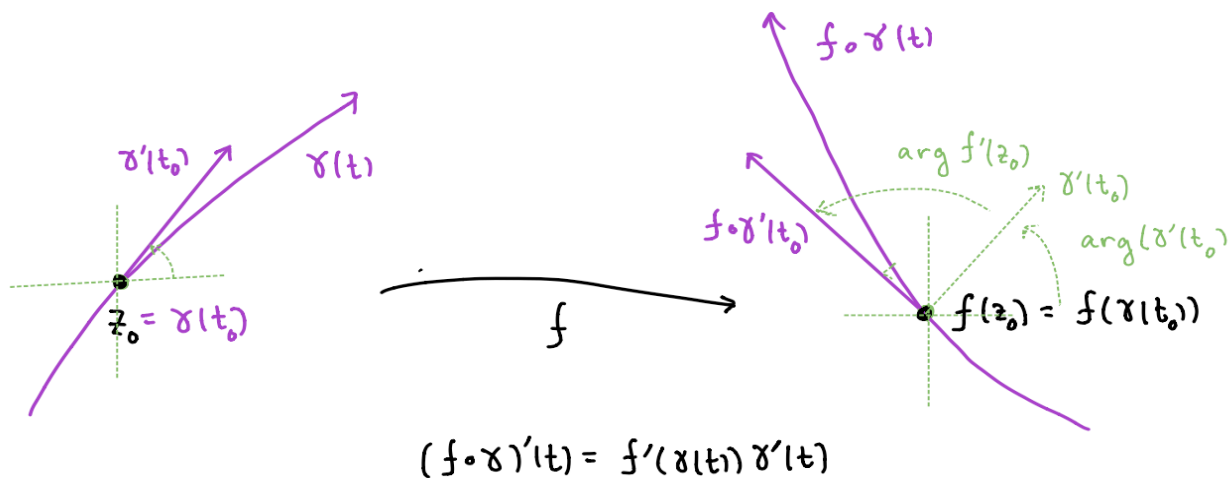
QED

2) Theorem (Chain rule for curves) If  $f$  is differentiable at  $z_0$  and  $\gamma: I \subseteq \mathbb{R} \rightarrow \mathbb{C}$  is a parametric curve  $\gamma(t) = x(t) + i y(t)$  such that  $\gamma(t_0) = z_0$  and such that  $\gamma'(t_0) = x'(t_0) + i y'(t_0)$  exists, then

$$(f \circ \gamma)'(t_0) = f'(\gamma(t_0)) \gamma'(t_0)$$

proof We can use the affine approximation formula for  $f$ , at  $\gamma(t_0)$ , and mimic the proof of Theorem 1.

Domain-range geometry implied by the chain rule for curves. Consider the curve  $\gamma(t)$  which has image in the domain of  $f$ , along with the curve  $f \circ \gamma(t)$  which has image in the range of  $f$ . Let  $f'(\gamma(t_0)) = r e^{i\theta}$ . Then the image curve tangent vector is obtained by rotating the original curve tangent vector by  $r$  and scaling it by  $\theta$ .



Conformal transformations and differential map discussion:

(i) The precise definition of the *tangent space* at  $z_0 \in \mathbb{C}$  is the set of all *tangent vectors* there, i.e. tangent vectors to curves passing through  $z_0$ :

$$T_{z_0} \mathbb{C} := \left\{ \gamma'(t_0) \mid \gamma \text{ is differentiable at } t_0 \text{ and } \gamma(t_0) = z_0 \right\}$$

(ii) If  $f(z)$  is a function from  $\mathbb{C}$  to  $\mathbb{C}$  that arises from a real-differentiable function  $F: A \subseteq \mathbb{R}^2 \rightarrow \mathbb{R}^2$ , then the *differential of  $f$  at  $z_0$*  is defined by

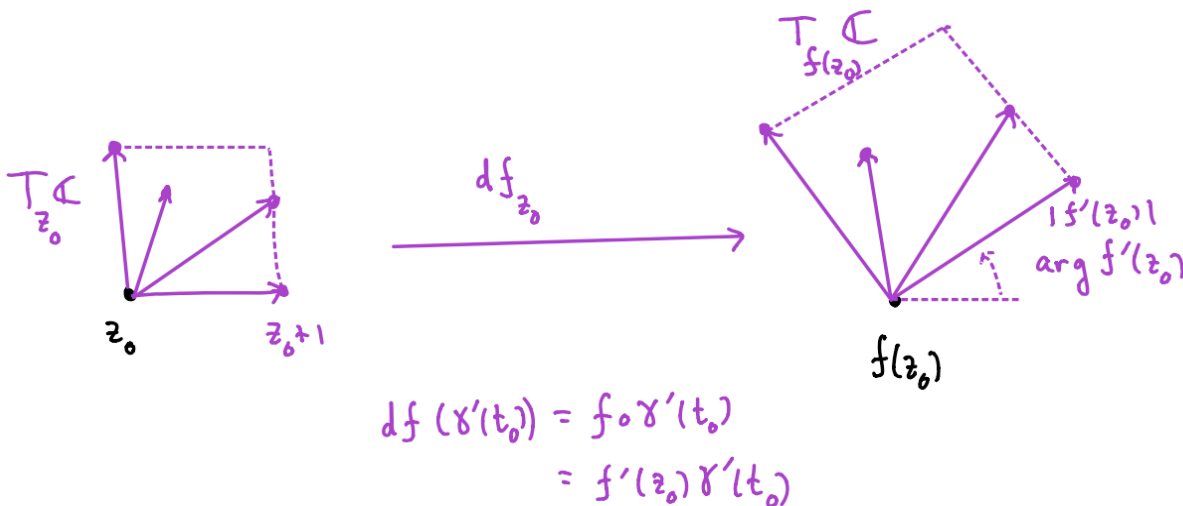
$$df_{z_0}(\gamma'(t_0)) := (f \circ \gamma)'(t_0).$$

$$df_{z_0}: T_{z_0} \mathbb{C} \rightarrow T_{f(z_0)} \mathbb{C}.$$

(iii) By the chain rule for curves, if  $f(z)$  is complex differentiable at  $z_0$ , then

$$df_{z_0}(\gamma'(t_0)) := (f \circ \gamma)'(t_0) = f'(z_0)\gamma'(t_0)$$

Geometrically, this means that for complex differentiable functions  $f$ , the differential map is a linear transformation from  $T_{z_0} \mathbb{C}$  to  $T_{f(z_0)} \mathbb{C}$  which is a rotation-dilation.



(iv) A function  $f: \mathbb{C} \rightarrow \mathbb{C}$  is called *conformal* at  $z_0$  iff its differential transformation preserves angles between tangent vectors. Since rotation-dilations have this property, a function  $f$  which is complex differentiable at  $z_0$ , and for which  $f'(z_0) \neq 0$ , is conformal at  $z_0$ . (It turns out that if  $f$  is conformal at  $z_0$  and also preserves orientations of pairs of tangent vectors, then  $f$  is complex differentiable at  $z_0$ .)

*Illustration.* Consider

$$f(z) = z^2, z_0 = 1 + i,$$

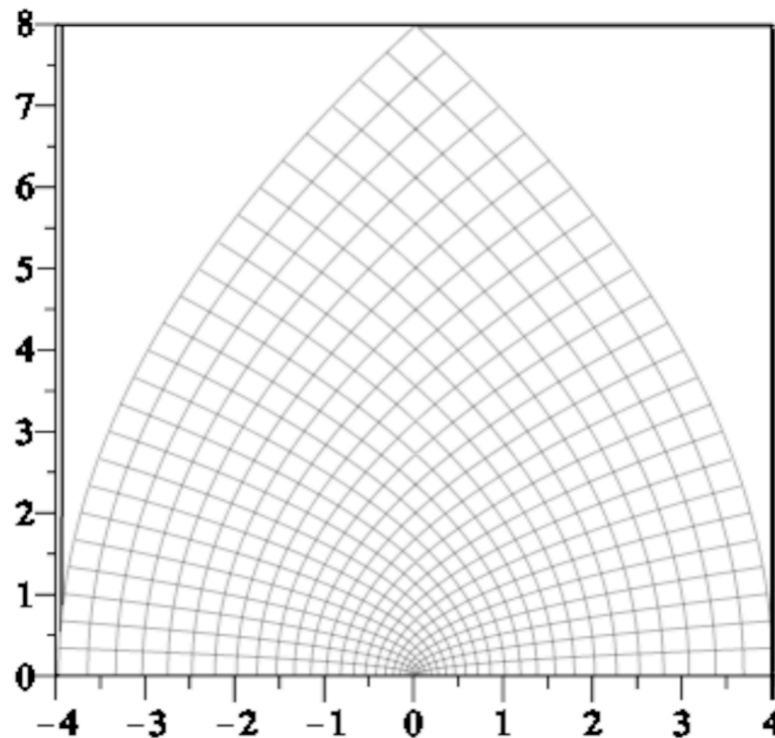
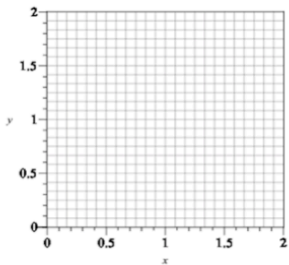
$$f(z_0) = 2i, f'(z_0) = 2 + 2i = 2\sqrt{2} e^{i\frac{\pi}{4}}$$

Below, are parts of a rectangular coordinate grid in the domain, and the image of that grid in the range space.

- Why are the images of the real and imaginary grid lines also perpendicular?
- Find the formula for the differential map

$$df_{z_0} : T_{z_0} \mathbb{C} \rightarrow T_{f(z_0)} \mathbb{C}$$

and illustrate the rotation dilation.



There is a local inverse function for analytic functions which we will prove on Wednesday next week using the local multivariable inverse function theorem you learned in Math 3220. I want to state it here, because it comes up in one of your homework problems for Wednesday. (You will only need to know the statement of the theorem, not its proof, for that problem.)

Theorem (Inverse function theorem) Let  $f$  be complex differentiable in a neighborhood of  $z_0$ , with  $f'(z_0) \neq 0$  and  $f'(z)$  continuous. Then there exist open sets  $U, V$  with  $z_0 \in U, f(z_0) \in V$  such that  $f: U \rightarrow V$  is a bijection and  $f^{-1}: V \rightarrow U$  is also analytic. Furthermore

$$(f^{-1})'(f(z)) = \frac{1}{f'(z)}$$

$\forall z \in U.$